ME/EE 106 - Fundamentals of Mechatronics Engineering  
Fall 2017

Instructor:  Winncy Du;  Office: E310F;  Phone: 408-924-3866;  Email: winncy.du@sjsu.edu
Office Hours:  M 9:00-10:00;W 9:00-10:00.

Class/Lab Meeting Information
ME106-01 (47647)/EE106-01 (49449) Seminar: MW 8:00 – 8:50 AM room E331
ME106-02 Lab (47648)/EE106-02 Lab (49450): Tu 1330 – 1515  E125
ME106-03 Lab (47649)/EE106-03 Lab (49451): W 1800 – 2045  E125
ME106-04 Lab (47654)/EE106-04 Lab (49452): Th 1800 – 2045  E125
ME106-05 Lab (47655)/EE106-05 Lab (49453): F 1430 – 1715  E125

NOTE: First lab meeting started in the week of 8/28/17

Lab TAs:  
Tu: 1:30-4:15 PM: Shrutika Pradhan (shrutika6293@gmail.com)
W: 6-8:45 PM: Tyler Sloan (tjsloan7670@gmail.com)
Th: 6-8:45 PM: Jonathan Dorsey (scramjet99@comcast.net)
Fr: 2:30-5:15 PM: Patrick Barrera (patrick.barrera23@gmail.com)

EE 98 and ME 30 (or CS 49C OR CMPE 30 OR CMPE 46) or their equivalents
(with a grade of ‘C-’ or better in each). For IT majors: TECH 60, MATH 71, CMPE
46 (with a grade of ‘C-’ or better in each). You must turn in an unofficial transcript
with the prerequisites highlighted by the second class period, or you will be dropped
from the class.

Prerequisites:

Course Description
Introduction to mechatronics with emphasis on analog electronics, digital electronics, sensors and transducers,
actuators, and microprocessors. Lectures are intended to provide the student with foundational concepts in
mechatronics and practical familiarity with common elements making up mechatronic systems. Laboratory
experiments are designed to give the student hands-on experience with components and measurement equipment
used in the design of mechatronic products. (3 units; lecture/lab).

Text (Required)

Hardware (Required)
Arduino microcontroller (Duemilanove or UNO R3). Sources: NKC Electronics, Adafruit Industries, Sparkfun
Electronics, Modern Device, sainsmart (Local: Jameco, Radio Shack, Fry’s Electronics). Ballpark price is $15-$30.

Weighting of Course Components and Grading Scheme
HW 10%;  Lab Report 15%;  Project 20%;  Two Midterms 15%;  Quizzes 5%;  Final Exam 20%;
Individual Performance on the Term Project 15%

A 100 – 93%;  A- 92 – 90%;  B+ 89 – 87%;  B 86 – 83%;  B- 82 – 80%;
To pass the course, you must earn at least a grade of C-.

Course Goals and Learning Objectives
The goals of this course are to help you:

1. Develop an understanding of the basic elements underlying mechatronic systems: analog electronics, digital
electronics, sensors, actuators, microcontrollers, and embedded software.
2. Understand how to interface electromechanical systems to microcontrollers.
3. Gain hands-on experience with commonly used electronic test and measurement instrumentation.
4. Improve written communication skills through laboratory and project reports.
5. Gain practical experience in applying knowledge gained in the course through a hands-on project.
Learning Objectives
The student who successfully completes the course will be able to:
1. Articulate what the essence of mechatronics is and provide examples of mechatronic systems.
2. Explain the concepts of input and output impedance, voltage division, and circuit loading.
3. Explain the concept and characteristics of a signal source.
4. Design and analyze the performance of RC low-pass and high-pass filter circuits.
5. Explain the basic structure of a microcontroller, the nature of IO ports, and the common peripheral subsystems found in most microcontrollers.
6. Write embedded software to successfully interact with sensors, power interfaces, analog and digital IO ports, and other peripheral elements in the control of a mechatronic system.
7. Explain what analog-to-digital-conversion (A/D) is and how to implement it using a microcontroller.
8. Select and configure operational amplifier circuits to achieve desired interfacing requirements between a signal source and a downstream device such as a microcontroller or data acquisition system.
9. Explain the practical limitations of operational amplifiers and quantitatively estimate the effects of these limitations on output voltage and current of the op-amp.
10. Explain the basic operation of bipolar and MOS field-effect transistors and design with them to activate solenoids, relays, motors, etc. from signal sources.
11. Explain the input/output characteristics of digital logic devices and design a logic circuit to accomplish a given task.
12. Explain the underlying operational principles and construction of electromagnetic actuators such as DC, AC, and stepping motors.
13. Determine the torque and speed requirements for a given motion control application considering system inertia, external forces or torques, and motion profiles and select an appropriate motor.
14. Function effectively as part of a team in carrying out laboratory experiments and open-ended projects.
15. Document a laboratory experiment and open-ended projects clearly and completely in written form.

Classroom Protocol/Code
Attendance to each lecture and lab is expected. No phone is activated and used during the lectures and labs. A missing lab may be made up only if a good reason is presented and the lab TA and the lab space is available. Homework (hardcopy) is generally assigned by Thursday and due next Tuesday. You must turn in your HW at the beginning of the lecture. No credit for late HW.
Laboratory reports (individual report, hardcopy) must be submitted at the beginning of the lab period to your lab instructor one week after the laboratory experiment was performed.

University Policies
University’s Academic Integrity policy (Important!) located at [www.sjsu.edu/studentconduct/docs/S07-2.pdf](http://www.sjsu.edu/studentconduct/docs/S07-2.pdf), requires you to be honest in all your academic course work. Faculty members are required to report all infractions to the office of Student Conduct and Ethical Development. Your commitment as a student to learning is evidenced by your enrollment at San José State University. The Student Conduct and Ethical Development website is available at [http://www.sjsu.edu/studentconduct/](http://www.sjsu.edu/studentconduct/). Instances of academic dishonesty will not be tolerated. Cheating on exams or plagiarism will result in a failing grade and sanctions by the University. For this class, all assignments are to be completed by the individual student unless otherwise specified.

Plagiarism is defined as, the use of another person’s original (not common-knowledge) work without acknowledging its source.\(^1\) Examples of plagiarism include, but are not limited to:\(^2\):
- copying in whole or in part, a picture, diagram, graph, figure, program code, algorithm, etc. and using it in your work without citing its source
- using exact words or unique phrases from somewhere without acknowledgement
- putting your name on a report, homework, or other assignment that was done by someone else

Several helpful resources can be found at:


\(^2\) Adapted from, “Avoiding Plagiarism,” [https://owl.english.purdue.edu/owl/resource/589/01/](https://owl.english.purdue.edu/owl/resource/589/01/).
SJSU Senate Policy S12-3 - Federal Regulation of the definition of the credit hour
For this class, it is expected that you will spend at least seven hours outside of class working on homework, lab work, project work, test preparation, etc. See: http://www.sjsu.edu/senate/docs/S12-3.pdf for more information.

Campus Policy in Compliance with the American Disabilities Act
Presidential Directive 97-03 requires that students with disabilities requesting accommodations must register with the AEC (Accessible Education Center) to establish a record of their disability.

Other Reminders
- All lectures are arranged to support the lab experiments. Be sure to understand the lectures before doing the lab.
- The pace of this class is relatively fast, especially if you have little prior experience with electronics, so don’t slack off.
- Start working on the projects as soon as possible. The most common lament heard from students who fare poorly in the class is, “We should have started earlier on the term project.”
- Lab experiments are intended to be performed in a group of two students (although the lab reports are wrote and submitted individually).
## Tentative Course and Lab Schedule

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<tr>
<th>WEEK #</th>
<th>LECTURE</th>
<th>Lab</th>
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| Week #1 08/23 | Enrollment, syllabus, course prerequisite, lab requirements (e.g., microcontrollers), pre-lab quizzes  
Ch. 1.1-1.2 Intro to mechatronics and measurement system; course overview | No lab                                   |
| Week #2 08/28, 08/30 | Ch. 7.1-7.2 Microprocessors, microcontroller, and microcomputer  
Introduction to the Arduino microcontroller, ATmega328P MCU | 1. Intro to Mechatronics Laboratory       |
| Week #3 09/06 | Ch. 4.1 – 4.4 System response; bandwidth RC filters; transfer functions  
Course project | 2. Intro to Arduino Microcontroller                                    |
| Week #4 09/11, 09/13 | Ch. 6.1-6.3 Digital representations, combinational logic  
I/O ports, digital I/O | 3. RC Filters                                                            |
| Week #5 09/18, 09/20 | Ch. 3.1 – 3.5 Semiconductor basic, diodes, transistors/MOSFET, photoresistors  
Ch. 9.1-9.2 Position sensors, drivers, interrupters | 4. Digital I/O                                                           |
| Week #6 09/25, 09/27 | Review for Exam#1  
Midterm Exam #1 | 5. Photoresistor, LED, and Transistor-A                                  |
| Week #7 10/02, 10/04 | Ch. 9.2 Optical encoder; PWM  
Ch. 10.5 DC motors, servo motors | 6. Photoresistor, LED, and Transistor-B                                  |
| Week #8 10/09, 10/11 | Ch. 10.5 Stepper motors  
Motor control and drivers | 7. Printer Carriage  
Motion Control                                                              |
| Week #9 10/16, 10/18 | Ch. 5.1-5.7 Op-amps, inverting/non-inverting op-amps, summer  
Ch. 5.8-5.14 Difference/instrumentation amps, integrator, S&H circuit, comparators | 8. Servo System Design                                                  |
| Week #10 10/23, 10/25 | Ch. 8.1-8.3 Quantizing theory, A/D conversion  
Ch. 8.4-8.6 D/A conversion, data acquisition, virtual instrumentation | 9. Stepping Motors                                                        |
| Week #11 10/30, 11/01 | Review for Exam#2  
Midterm Exam #2 | 10. Electronic Scale                                                   |
| Week #12 11/06, 11/08 | Ch. 6.4-6.8 Boolean algebra, logical network, truth table, sequential logic  
Ch. 6.9-6.11 Flip-Flops, TTL & CMOS circuits | Project work – open lab                                              |
| Week #13 11/13, 11/15 | Ch. 10.1-10.3 Actuating principles & devices (solenoids, relays, motors)  
Ch. 9.3-9.7 Other sensors: stress/strain/temperature | Project work – open lab                                              |
| Week #14 11/20 | Thanksgiving Holiday | Project work – open lab                                              |
| Week #15 11/27, 11/29 | Term Project Presentation I (E331)  
Term Project Presentation II (E331) | Project work – open lab                                                |
| Week #16 12/04, 12/06 | Term Project Demonstration (E125 and nearby area) |                                                                 |
| Week #17 12/11 | Course Review |                                                                 |

**Term Project Demonstration: 8-11 am, Wednesday, Dec. 4 & 6 (E125 and nearby area)**

**Final Exam: 7:15-9:30, Thursday, Dec. 14, E331**