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# Dynamic Signals

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# Static vs. Dynamic Signals

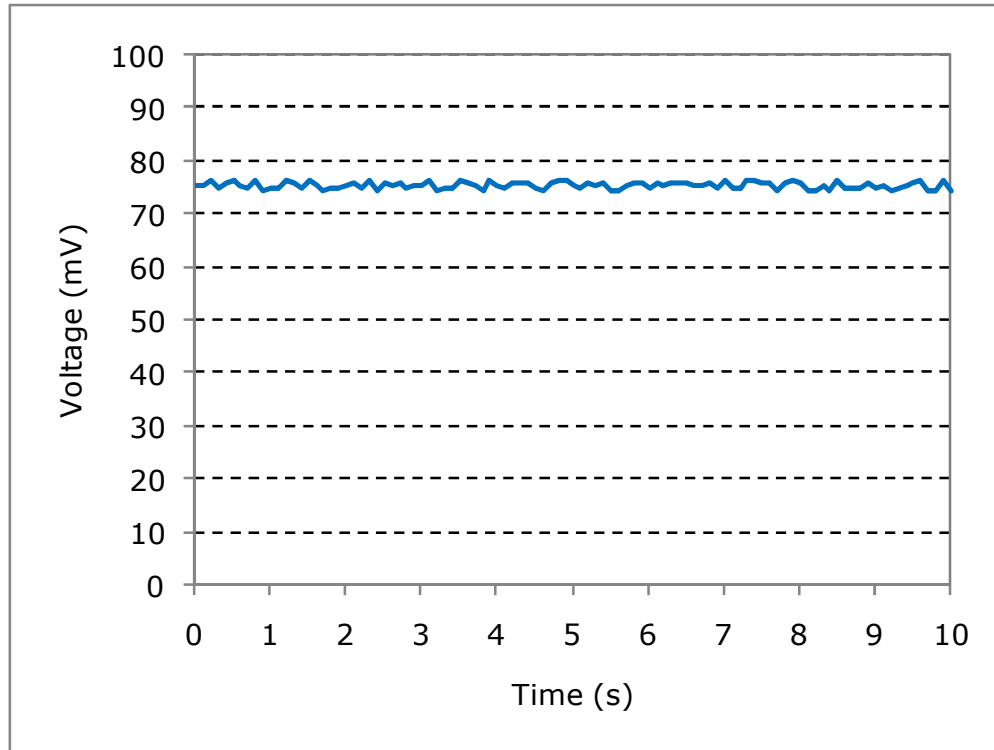
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- ❑ In principle, all signals are dynamic; they do not have a perfectly constant value over time.
- ❑ **Static** signals are those for which changes over time are negligible for the intended measurement.
- ❑ **Dynamic** signals are those for which changes over time are relevant for the intended measurement.

Examples include:

- Impulses, steps, ramps
- Periodic functions (e.g. sinusoidal)
- Random noise

# Repeatability Error and Time

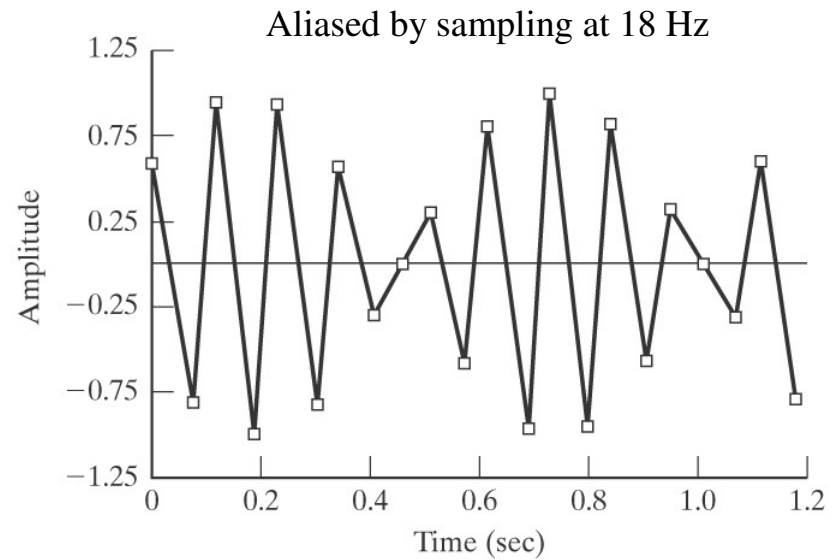
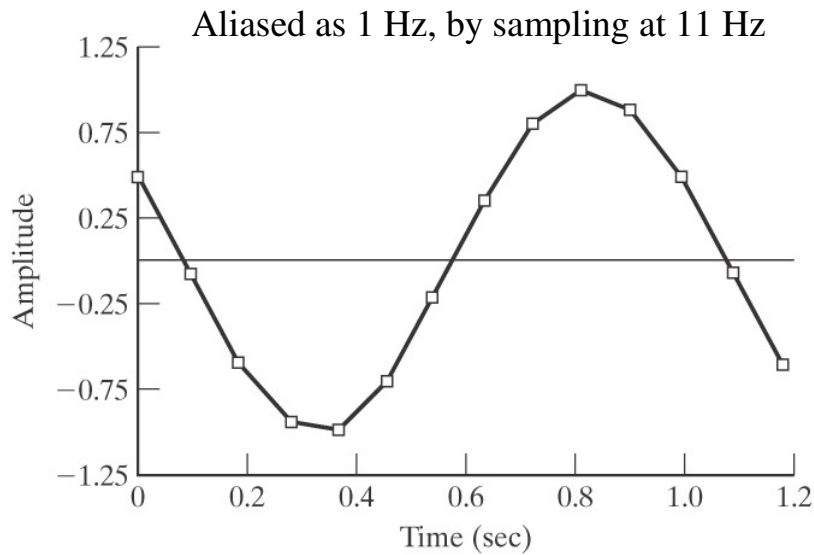
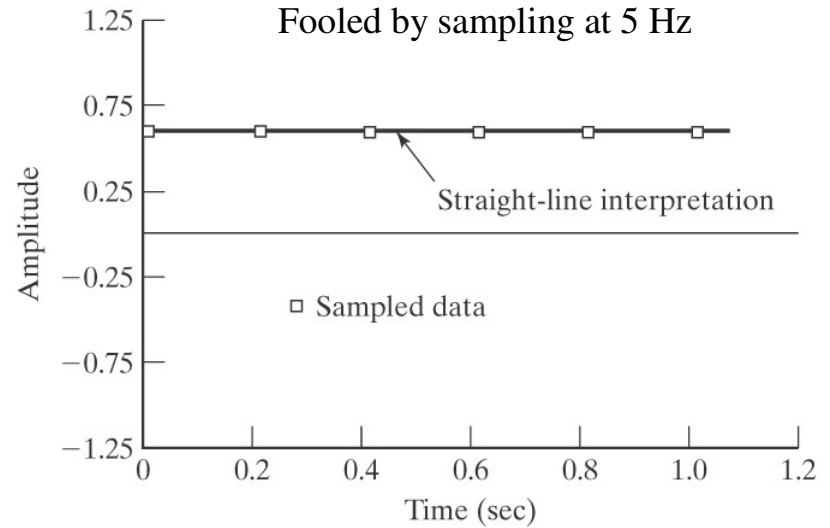
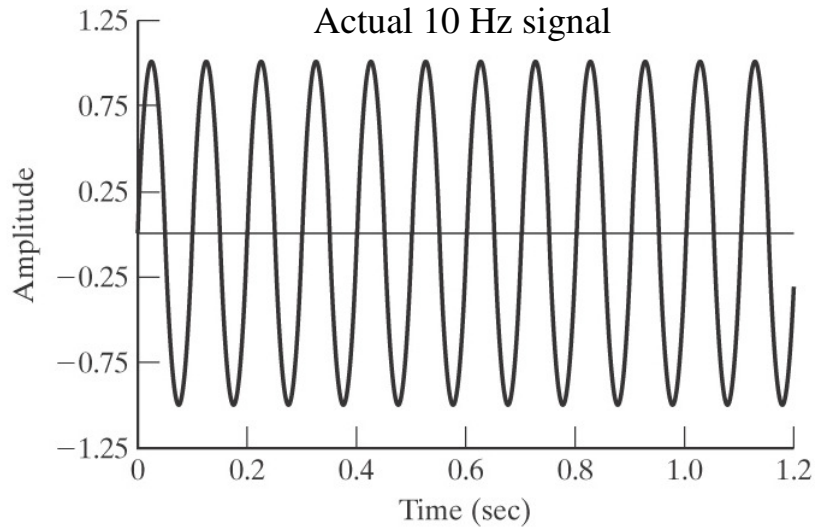


Root Mean Square:

$$\text{RMS} = \sqrt{\frac{1}{n} \sum_{i=1}^n y_i^2}$$

□ What is the value of this signal?

# Discrete Sampling Rate Limitations



# Sampling-Rate Theorem

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- The sampling-rate theorem states that the sampling frequency  $f_s$  must be greater than twice the actual signal frequency  $f$  to correctly determine the frequency of the actual signal:

$$f_s > 2f$$

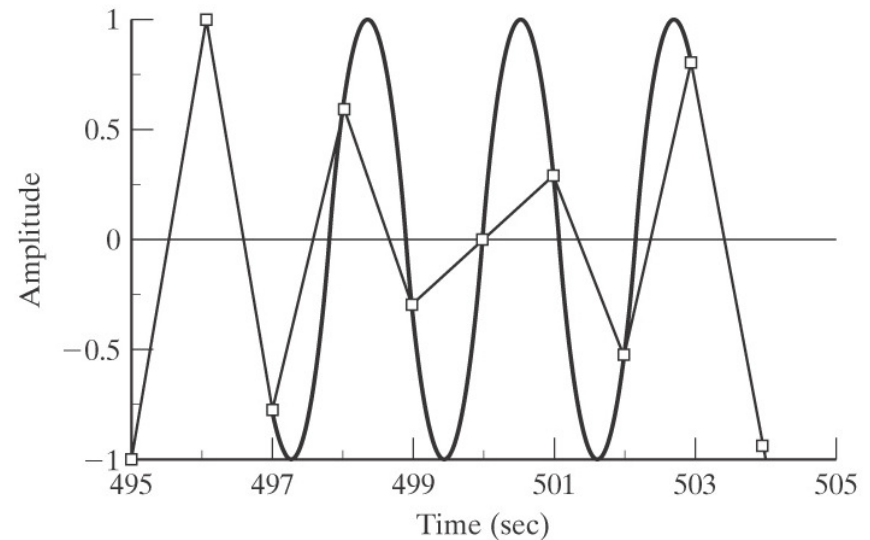
- For signals containing more than one characteristic frequency, it applies to the highest frequency.
- It is not unusual for actual signals to have frequencies too high to set sampling frequency greater than  $2f$ , in which case filters may be necessary.
- Names associated with the sampling-rate theorem include Nyquist, Shannon, and Cauchy, but this theorem must not be confused with the “Nyquist Stability Criterion” from controls theory.

# Reconstructing Waveforms

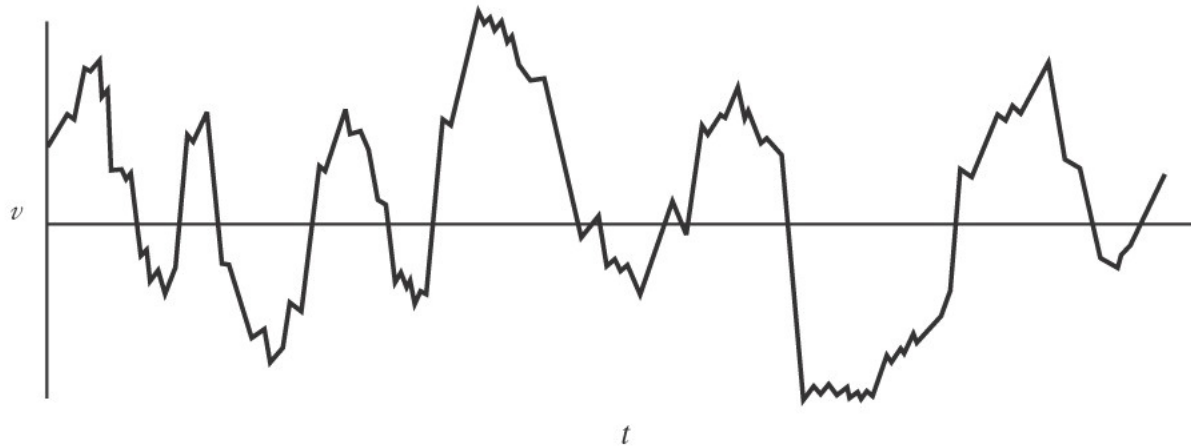
- ❑ Even if the sampling-rate theorem condition is met such that  $f_s > 2f$ , the sampled data does not necessarily reveal the same amplitude as the actual signal.
- ❑ However (amazingly) if the data set is sufficiently large, the original waveform can be reconstructed with high fidelity from the  $n$  available measurements by using the following series equation:

$$x\{t\} = \frac{1}{\pi} \sum_{n=-\infty}^{+\infty} x\{n\Delta T\} \frac{\sin[\pi(t/\Delta T - n)]}{t/\Delta T - n}$$

$$\Delta T = 1/f_s$$



# Spectral Analysis



- **A general Time Varying signal does not have the form of a simple sine wave**
- **Complicated waveforms can be considered to be a sum of set of sine or cosine waves of different frequencies**
- **Process of determining => Spectral analysis**

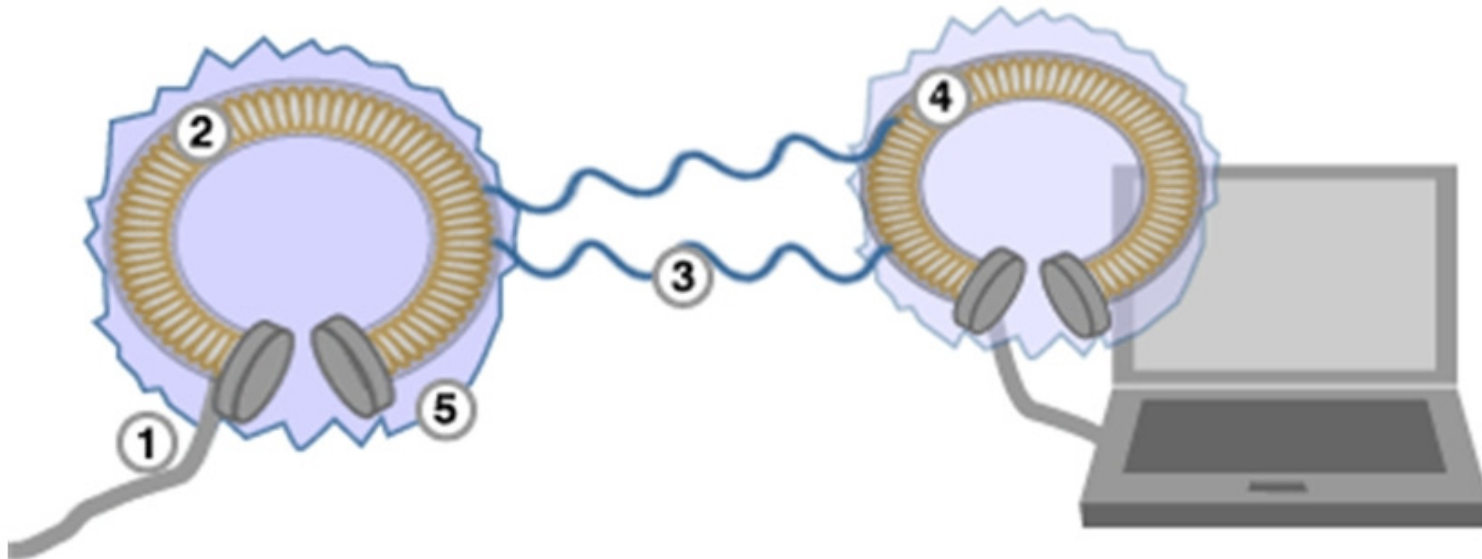
# Examples of Spectral Analysis Applications

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- ❑ Vibration measurement
- ❑ Structural design & fatigue analysis
- ❑ Noise cancellation
- ❑ Sensitive resonance-based transducers
- ❑ Wireless power sources

# Example of Applied Frequency Analysis

## HOW WIRELESS POWER COULD WORK



- ♦ **1)** Power from mains to antenna, which is made of copper
- ♦ **2)** Antenna resonates at a frequency of 6.4MHz, emitting electromagnetic waves
- ♦ **3)** 'Tails' of energy from antenna 'tunnel' up to 5m (16.4ft)
- ♦ **4)** Electricity picked up by laptop's antenna, which must also be resonating at 6.4MHz. Energy used to re-charge device
- ♦ **5)** Energy not transferred to laptop re-absorbed by source antenna. People/other objects not affected as not resonating at 6.4MHz

# Fourier Series

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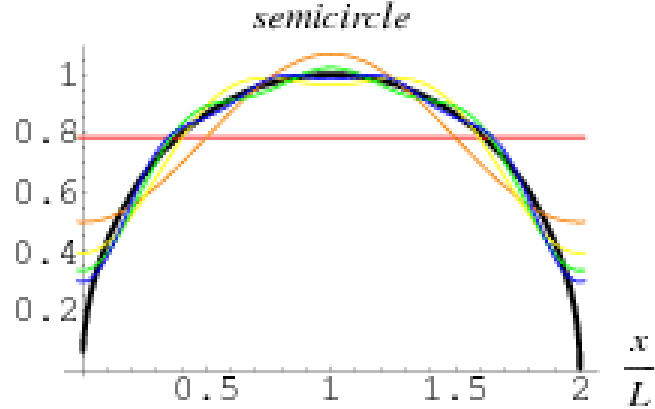
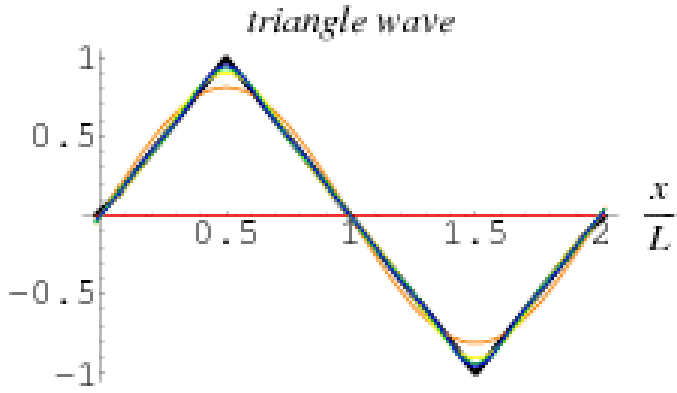
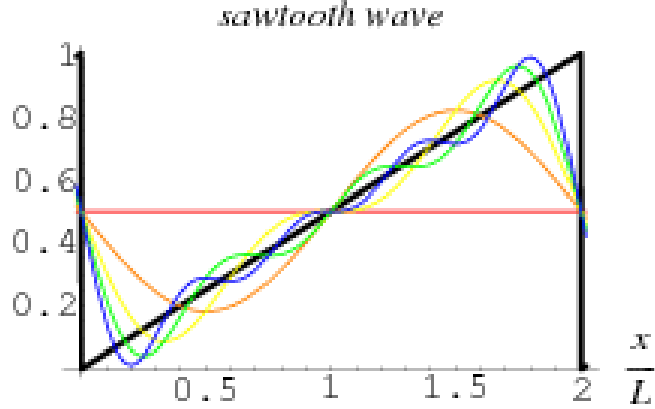
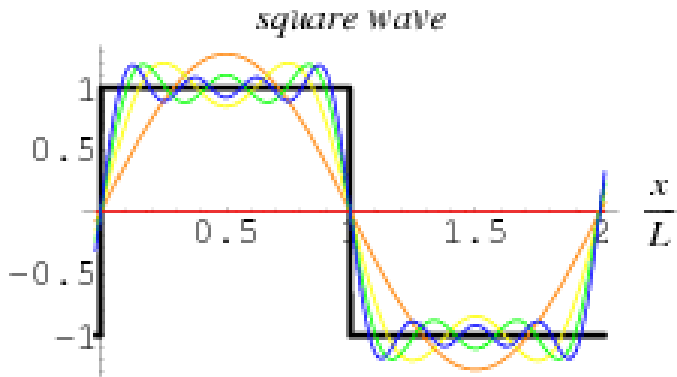
- Any periodic function  $x\{t\}$  can be represented by a Fourier series with period  $T = 1/f$  and fundamental angular frequency  $\omega_0 = 2\pi f_0$ .

$$x\{t\} = A_0 + \sum_{n=1}^{\infty} [A_n \cos(n\omega_0 t) + B_n \sin(n\omega_0 t)]$$

$$A_0 = \frac{1}{T} \int_0^T x\{t\} dt \quad A_n = \frac{2}{T} \int_0^T x\{t\} \cos(n\omega_0 t) dt \quad B_n = \frac{2}{T} \int_0^T x\{t\} \sin(n\omega_0 t) dt$$

- Furthermore, dynamic signals that are not periodic can be constructed by superposition of harmonics...

# Examples of Summed Harmonics



# Fourier Transform

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- As opposed to the limited case of summations in Fourier series, the Fourier transform is more useful because it treats frequency as a continuous function.

$$F\{\omega\} = \int_{-\infty}^{+\infty} f\{t\}e^{-j\omega t} dt$$

- The magnitude of  $F\{\omega\}$  at any given frequency  $f\{t\}$  along the spectrum reveals the relative contribution of that particular frequency to the original signal.
- Having a Fourier transform  $F\{\omega\}$ , the original function  $f\{t\}$  can be recovered by the inverse Fourier transform:

$$f\{t\} = \frac{1}{2\pi} \int_{-\infty}^{+\infty} F\{\omega\}e^{j\omega t} d\omega$$

# Discrete Fourier Transform

- Necessary for discrete sampling, the discrete Fourier transform is defined in terms of the finite number of  $N$  samples during an overall time period  $T$ , with time increment  $\Delta t$  and frequency increment  $\Delta f = 1/T$ .

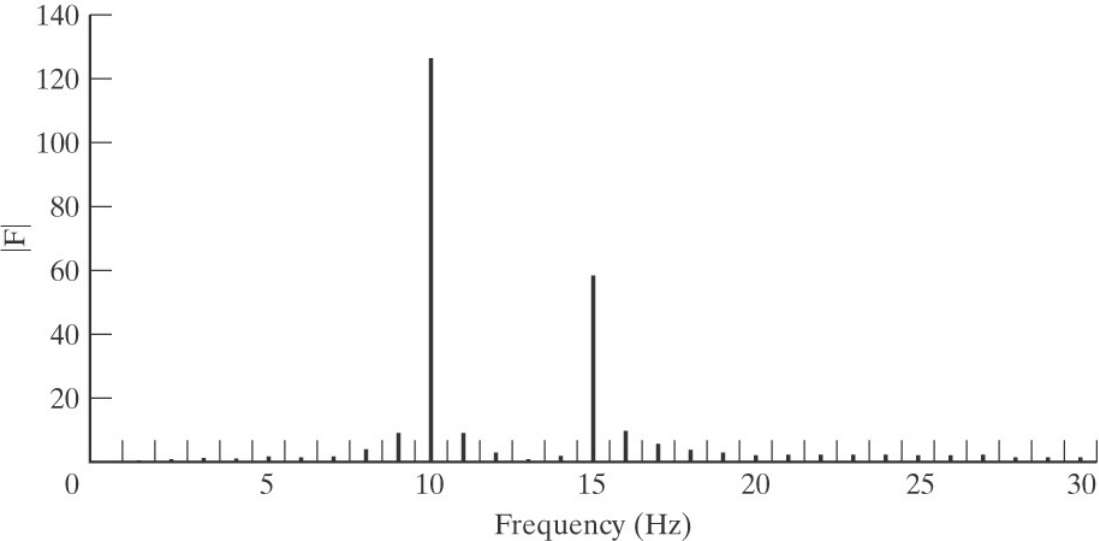
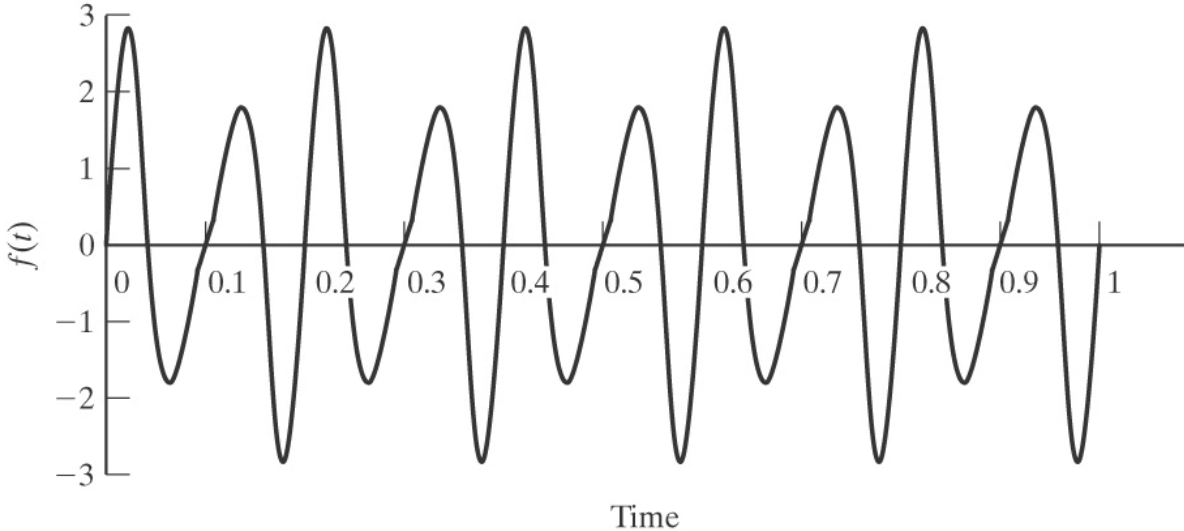
$$F\{k\Delta f\} = \sum_{n=0}^{N-1} f\{n\Delta t\} e^{-j(2\pi k\Delta f)(n\Delta t)} \quad k = 0, 1, 2, \dots, N-1$$

- As in the case for (continuous) Fourier transforms, having  $F\{k\Delta f\}$  provides a way to recover the original function  $f\{n\Delta t\}$  using an inverse transform:

$$f\{n\Delta t\} = \frac{1}{N} \sum_{k=0}^{N-1} F\{k\Delta f\} e^{j(2\pi k\Delta f)(n\Delta t)} \quad n = 0, 1, 2, \dots, N-1$$

- The Fast Fourier Transform (FFT) is a very effective and popular algorithm to compute discrete Fourier transforms.

# FFT Example



# Summary

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- ❑ If a Fourier series is a summation, and a Fourier transform is superior because it treats frequency as continuous throughout a spectrum,
  
- ❑ And a discrete Fourier transform is necessary because of discrete (computerized) sampling,