

Physics 51 "Study Guide" for Final ("Laundry List" of important concepts) Todd Sauke

Concept (important concepts in bold; vectors also shown in bold) **Symbol or Equation**

Prerequisites:

Physics quantities are typ. either scalars or vectors (magnitude & direction)	<i>components</i> of vectors add
From mechanics , total external force on a body = mass x acceleration	$\Sigma \mathbf{F}_{\text{ext}} = m \mathbf{a}$ (SI newton, "N")
Mass (SI kilogram, "kg") resists change in motion (via " momentum ", p)	$\mathbf{p} = m\mathbf{v}$, $\mathbf{F}_{\text{ext}} = d\mathbf{p}/dt$
A mass moving in a circle undergoes centripetal acceleration	$a_{\text{centr}} = v^2 / r$
Conservation of linear momentum : Isolated system ($\Sigma \mathbf{F}_{\text{ext}} = 0$) $\rightarrow \Delta \mathbf{p} = 0$; $\mathbf{p}_f = \mathbf{p}_i$	$m_1 \mathbf{v}_{f1} + m_2 \mathbf{v}_{f2} = m_1 \mathbf{v}_{i1} + m_2 \mathbf{v}_{i2}$
A moving mass has energy of motion, " Kinetic Energy " (SI joule, "J")	$KE = \frac{1}{2} m v^2$ (a scalar)
A spring being compressed pushes back proportional to compression	$\mathbf{F} = -k \mathbf{x}$
A compressed spring has energy of compression, elastic " Potential Energy "	$U = \frac{1}{2} k x^2$
For conservative forces, mechanical energy is conserved	$E = KE + PE = \text{constant}$ ($W_{nc} = 0$)

Electromagnetics:

Electric Charge is the fundamental quantity in Electrostatics	Q (SI coulomb, "C")
Charge is conserved, quantized, and comes in "positive" and "negative"	$e = 1.602 \times 10^{-19} \text{ C}$
Like charges repel (radially); opposite charges attract; Coulomb's Law	$F = 1/(4 \pi \epsilon_0) q_1 q_2 / r^2$
The constant ϵ_0 is numerically related (by definition) to the speed of light, c	$\epsilon_0 = 10^7 / (4 \pi c^2) = 8.854 \times 10^{-12}$
All "normal" matter is made up of protons , neutrons and electrons	Coulomb's $k = 1/(4 \pi \epsilon_0) = 8.99 \times 10^9$
Protons have +e charge; electrons have -e. Their mutual attraction holds everything together. In a conductor, electrons are free to move around.	$m_p = 1.67 \times 10^{-27} \text{ kg}$
Total force (vector) is the vector sum of individual forces (superposition)	$m_e = 9.11 \times 10^{-31} \text{ kg}$
The Electric field vector is the force per unit charge on a "test charge", q_0	$\mathbf{F} = \Sigma \mathbf{F}_i$
For distributions of charge (eg. λ , σ), vector integrate over the distribution	$\mathbf{E} = \mathbf{F}_0 / q_0$ $\mathbf{F} = q \mathbf{E}$
Field lines provide a graphical representation of E (and B) fields	$\mathbf{E} = \int d\mathbf{E} = \int dq / (4 \pi \epsilon_0 r^2) \hat{\mathbf{r}}$
An Electric Dipole is a separation of equal magnitude, opposite charges	E strong where lines are dense
An Electric Dipole, p , in an Electric field, E , experiences a torque	$\mathbf{p} = q\mathbf{d}$ (d =separation - $\rightarrow +$)
An Electric Dipole oriented in an Electric field has potential energy, U	$\boldsymbol{\tau} = \mathbf{p} \times \mathbf{E}$ $\tau = p E \sin(\phi)$
Electric Flux ; "flow" of E through a surface. (dA is a vector \perp to surface)	$U = -\mathbf{p} \cdot \mathbf{E} = -p E \cos(\phi)$
Gauss's Law expresses the fact that the source of (static) flux is charge	$\Phi_E = \int \mathbf{E} \cdot d\mathbf{A}$ (through surface)
Charge on a conductor at rest resides on its <i>surface</i> . Also for conductor \rightarrow	$\Phi_E = \int \mathbf{E} \cdot d\mathbf{A} = Q_{\text{encl}} / \epsilon_0$
Use Gauss's Law to determine E field for symmetric charge distributions	$\mathbf{E}_{\text{inside}} = 0$ (for static case)
Gauss's Law easily shows E from a line of charge (instead of nasty integral)	eg. $E = \sigma / 2\epsilon_0$ (for sheet)
A symmetric distribution will be easier to solve for E using Gauss's Law	$E = \lambda / (2 \pi \epsilon_0 r)$
Electric force from a static charge distribution is a conservative force	eg. $E = \sigma / \epsilon_0$ (between two cond. plates)
Work done on "test charge" is path-independent change in potential energy	$U = qV$ $U = q_0 / (4 \pi \epsilon_0) \Sigma q_i / r_i$
Electric Potential is potential energy per unit charge (SI volt, "V")	$V = U/q$ $V = 1 / (4 \pi \epsilon_0) \Sigma q_i / r_i$
We always speak of " potential difference " (the zero is chosen for convenience)	$V_a - V_b = \int \mathbf{E} \cdot d\mathbf{l}$
The reverse of this is that E field is the (minus) gradient of the potential	$\mathbf{E} = -\text{Grad} (V)$
Equipotential surfaces are everywhere perpendicular to the E field lines	
A capacitor (any pair of separated conductors) holds charge per volt	$C = Q / V_{ab}$ (SI farad, "F")
Capacitance depends ONLY on geometry (& what's between conductors)	$C = \epsilon_0 A / d$ (parallel plates)
When capacitors are connected in parallel , the equivalent capacitance is:	$C_{\text{eq}} = C_1 + C_2 + C_3 + \dots$
When in series , capacitors have an equivalent capacitance given by:	$1/C_{\text{eq}} = 1/C_1 + 1/C_2 + 1/C_3 + \dots$
It takes work (energy) to charge a capacitor. W = potential energy, U	$U = \frac{1}{2} Q^2 / C = \frac{1}{2} C V^2 = \frac{1}{2} Q V$
Energy (U) stored in a capacitor " resides " in the electric field	$u = \frac{1}{2} \epsilon_0 E^2$ ($u = U$ -density)
If the insulation separating capacitor conductors is dielectric, not vacuum:	just replace ϵ_0 with $\epsilon = k \epsilon_0$!

Current is the amount of charge flowing through an area per unit time
In a conductor (non-static case now!), free charges (typ. electrons) can move (with drift velocity, v_d) in response to an Electric field

The current per unit area is called **current density** (a vector!)

Even conductors have resistance to the flow of charge (material dependent)

The resistivity of a material is temperature dependent, typ. increasing w/ T

A source of **electromotive force** (emf or \mathcal{E}) makes current flow in a circuit

For materials obeying **Ohm's Law**, current is proportional to voltage

The ratio V/I is called **resistance** and is related to a material's resistivity

Current flowing through a resistor is accompanied by a **voltage drop**

An "ideal" source of emf supplies a perfectly constant voltage to the circuit

A real source of emf (eg. a battery) has **internal resistance**, r (voltage drop)

A circuit element with potential difference, V_{ab} , across it and current, I ,

flowing through it is a source or sink of **power** depending on sign of I

When resistors are connected in **series**, the **equivalent resistance** is:

When in **parallel**, resistors have an **equivalent resistance** given by:

Series resistors all have the same current; when in parallel, the same voltage

Kirchhoff's junction rule (based on conservation of charge)

Kirchhoff's loop rule (based on conservation of energy)

Use Kirchhoff's rules to generate equations ("n equations in n unknowns")

An "ideal" ammeter has zero resistance and measures the current through it

An "ideal" voltmeter has ∞ r_{in} & measures voltage across probed points

When a circuit ("**RC circuit**") has a capacitor being charged or discharged

by a series resistor, the current and charge are not constant. Kirchhoff's

loop-rule equation for the circuit results in a differential equation,

the solution of which involves decaying exponentials:

The product of R & C has units of time and is called the "**time constant**" τ

Magnetic interactions are interactions between **moving** charged particles

Magnetic interactions are described by the **vector** field, \mathbf{B} (SI tesla, "T")

The magnetic force is **always perpendicular** to \mathbf{v} (and \mathbf{B}): no work done

Just like for \mathbf{E} , field lines provide a graphical representation of \mathbf{B} fields

Magnetic Flux; "flow" of \mathbf{B} through a surface (again, just like with \mathbf{E})

Gauss's law for magnetism: there are **no "magnetic monopoles"**

In a uniform \mathbf{B} field: charged particle goes in circle (or spiral) of radius, R

Crossed \mathbf{E} and \mathbf{B} fields: velocity selector (when $F_{net}(v) = 0$, no deflection)

For a current carrying wire in a magnetic field, there is a force on the wire

A current loop of area A & current I in a uniform magnetic field \mathbf{B} has $\mathbf{F}_{net} = 0$

But it does experience a torque, τ , in terms of magnetic moment, μ .

The work done by the torque can be described as a potential energy

A moving charge q with velocity \mathbf{v} creates a magnetic field \mathbf{B} that depends

on distance as $1/r^2$, & is perpendicular to both \mathbf{v} and $\hat{\mathbf{r}}$ the **unit** vector
from the "source point" (at q) **to** the "field point" (at \mathbf{B}).

The constant μ_0 is defined so that, together with ϵ_0 , they relate to c

The total \mathbf{B} from several moving charges is the vector sum of the fields

produced by the individual charges (**superposition**)

The **Biot-Savart law** gives the previous relations in terms of current in wire

$I = dQ/dt$ (SI ampere, "A")

$I = n q v_d A$ (A = area)

(above: n = charge density)

$\mathbf{J} = n q \mathbf{v}_d$

$\rho = E / J$ (ρ = "**resistivity**")

$\rho(T) = \rho_0 [1 + \alpha (T - T_0)]$

\mathcal{E} is provider of voltage, V

$V = I R$

$R = \rho L / A$ (SI ohm, " Ω ")

label R w/ '+' & '-' in diagrams!

$V_{ab} = \mathcal{E} - I r$

$P = V_{ab} I = I^2 R = V^2 / R$ (SI watt, "W")

(a resistor **always** takes energy out)

$R_{eq} = R_1 + R_2 + R_3 + \dots$

$1/R_{eq} = 1/R_1 + 1/R_2 + 1/R_3 + \dots$

$\sum I = 0$

$\sum V = 0$

$\Delta V_{ammeter} = 0$

$I_{in_voltmeter} = 0$ (admits **no** current)

$q = C \mathcal{E} (1 - e^{-t/(RC)}) = Q_f (1 - e^{-t/(RC)})$

$i = I_0 e^{-t/(RC)}$ (for charging)

$q = Q_0 e^{-t/(RC)}$

$i = I_0 e^{-t/(RC)}$ (for discharging)

$\tau = RC$, (in $e^{-t/\tau}$)

$\mathbf{F} = q \mathbf{v} \times \mathbf{B}$ (**right-hand-rule**)

\mathbf{B} field lines form **closed** loops

$\Phi_{mag} = \int \mathbf{B} \cdot d\mathbf{A}$

$\oint \mathbf{B} \cdot d\mathbf{A} = 0$ (closed surface)

$R = mv / (qB)$; $\omega = qB / m$

$v_{selected} = E / B$

$\mathbf{F} = \int d\mathbf{F} = \int I d\mathbf{l} \times \mathbf{B}$

$\mu = n I A$ (for n loops)

$\tau = \mu \times \mathbf{B}$ $\tau = \mu B \sin(\phi)$

$U = -\mu \cdot \mathbf{B} = -\mu B \cos(\phi)$

$\mathbf{B} = (\mu_0 / 4\pi) q \mathbf{v} \times \hat{\mathbf{r}} / r^2$

$\mu_0 = 4 \pi \times 10^{-7}$

$c^2 = 1 / (\epsilon_0 \mu_0)$

$\mathbf{B} = \int d\mathbf{B} = \int (\mu_0 / 4\pi) dq \mathbf{v} \times \hat{\mathbf{r}} / r^2$

$\mathbf{B} = \int d\mathbf{B} = \int (\mu_0 / 4\pi) I d\mathbf{l} \times \hat{\mathbf{r}} / r^2$

From this law, the **B** field from a long, straight current carrying wire is:
and the **right-hand-rule** gives the direction that **B** curls around the wire
The force per length between two long, parallel current carrying wires is
attractive if currents are in the same direction, repulsive if opposite

B at distance x along axis of conducting loop (N turns, radius a, current I)

Ampere's Law relates the line integral of **B** around any closed path to the
net current through any area bounded (encircled) by the path

We apply Ampere's law to a highly symmetric situation where we can choose the
integration loop (through field point P) to have constant B aligned with the path (or \perp)

The **B** field inside of a long solenoid with n turns per unit length is:

B inside a toroidal solenoid (N turns) at distance r from symmetry axis:

B field outside the space enclosed by a tightly wound solenoid is near 0

B field **inside** a long cylindrical conductor of radius R is easy using Ampere's Law

When magnetic materials are present, there is an effect on the B field

Changing **B** flux (Φ_B) through a closed loop induces emf (**Faraday's Law**)

The minus sign is **Lenz's Law**; induced current or \mathcal{E} **opposes** the change

A "search coil" with N loops of area A, and resistance R, can be used to measure B fields

Motional emf is caused by a conductor moving in a magnetic field

Associated with the induced emf is an induced **E** field (non-conservative)

A time-varying electric field generates a "**displacement current**", i_d

$$B = \mu_0 I / (2\pi r) \text{ (at distance } r)$$

$$F / L = \mu_0 I I' / (2\pi r)$$

$$B_x = \mu_0 N I a^2 / 2 (x^2 + a^2)^{3/2}$$

$$\oint \mathbf{B} \cdot d\mathbf{l} = \mu_0 I_{\text{enc}} \text{ (closed loop)}$$

I_{enc} includes displacement current

Choose integration *path* through P
to make the integral easy

$$B = \mu_0 n I \text{ (near the center)}$$

$$B = \mu_0 N I / (2\pi r)$$

$$B \approx 0 \text{ (outside solenoid)}$$

$$B = \mu_0 I r / (2\pi R^2) \text{ inside cylinder}$$

$$\text{just replace } \mu_0 \text{ with } \mu = K_m \mu_0!$$

$$\mathcal{E} = -d\Phi_B / dt$$

(lest the universe explode)

$$Q_{\text{transferred}} = B A N / R$$

$$\mathcal{E} = \int (\mathbf{v} \times \mathbf{B}) \cdot d\mathbf{l}$$

$$\mathcal{E} = \int \mathbf{E} \cdot d\mathbf{l} = -d\Phi_B / dt$$

$$i_d = \epsilon d\Phi_E / dt$$

The fundamental relations between electric and magnetic fields have
been presented, but are collected together again here to show the unity
and symmetry of the relations. They are called **Maxwell's Equations**
and together form a **complete basis** for all of **electromagnetism**.

For reference, full force equation is repeated here (completes all of E&M)

$$\oint \mathbf{E} \cdot d\mathbf{A} = Q_{\text{encl}} / \epsilon_0$$

$$\oint \mathbf{B} \cdot d\mathbf{A} = 0$$

$$\oint \mathbf{B} \cdot d\mathbf{l} = \mu_0 (I_c + \epsilon_0 d\Phi_E / dt)_{\text{enc}}$$

$$\oint \mathbf{E} \cdot d\mathbf{l} = -d\Phi_B / dt$$

$$\mathbf{F} = q (\mathbf{E} + \mathbf{v} \times \mathbf{B})$$

Changing currents in circuits with shared magnetic flux induce emf in one
another. **Mutual inductance** M (SI henry, "H") is geometry dependent.
A changing current, i, in any circuit causes a self-induced emf \mathcal{E}

The self **inductance**, L (SI henry, "H") is enhanced by number N of loops

An **inductor** is a circuit device intended to have substantial inductance

The "-" sign (again Lenz's Law) means that an inductor opposes current change

An inductor (L) carrying current I has **energy associated with the B field**

If what's inside an inductor is not vacuum, replace μ_0 with μ (permeability)

When a circuit ("**RL circuit**") has an inductor connected to an emf and a
series resistor, the current is not constant. Kirchhoff's loop-rule equation
for the circuit gives a diff. eq., with decaying exponential solutions.

When a circuit ("**LC circuit**") has an inductor (L) and capacitor (C), it

has electrical oscillations **analogous** to a mechanical harmonic oscillator

L is analogous to mass m; $1/C$ is like the spring constant k; q is like x; i like v

Many other analogies hold; $L i (= L dq/dt)$ is like $m dv/dt = mv$ (momentum) and

it requires an **electromotive force** (voltage) to change it (like **force** changing **p**)

For the LC circuit, the energy exchanges back and forth (in the E, B fields)

When you add resistance R ("**LRC circuit**") the oscillations (of ω') decay in time

For small enough R, circuit is "underdamped"; for $R^2 = 4L/C \rightarrow$ "critical damping", $\omega' = 0$

$$\mathcal{E}_2 = -M di_1/dt; \mathcal{E}_1 = -M di_2/dt$$

$$\text{eg. } M = N_2 \Phi_{B2}/i_1 = N_1 \Phi_{B1}/i_2$$

$$\mathcal{E} = -L di/dt$$

$$L = N \Phi_B / i$$

again lest the universe explode

$$U = \frac{1}{2} L I^2$$

$$u = \frac{1}{2} B^2 / \mu_0 \text{ (} u = \text{U-density)}$$

$$i = \mathcal{E} / R (1 - e^{-tR/L}) = I_f (1 - e^{-tR/L})$$

$$i = I_0 e^{-tR/L} \text{ (with no emf)}$$

$$\tau = L/R, \text{ (in } e^{-t/\tau})$$

$$i = I \cos(\omega t + \phi)$$

$$\omega = \sqrt{1/LC} \text{ (}\omega \text{ in radians / s)}$$

$$U = \frac{1}{2} L I^2 \text{ is like } KE = \frac{1}{2} m v^2$$

$$F = ma (= m dv/dt) \text{ is like } V = L di/dt$$

label L and C with '+' & '-'

$$i = I e^{-tR/(2L)} \cos(\omega' t + \phi)$$

$$\omega' = \sqrt{(1/LC - R^2/(4L^2))}$$

An ac source produces an emf that varies sinusoidally with time. We can represent an sinusoidal voltage or current with a **phasor vector** rotating counterclockwise with ang. freq. ω . Instantaneous quantity is x projection

In general, the (sinusoidal) voltage can be "out of phase" with the current
The voltage v across a resistor is "**in phase**" with the i (power is dissipated)
The v across an inductor "**leads**" the current i by 90° (no power dissipated)
The v across a capacitor "**lags**" the current i by 90° (no power dissipated)

X_L and X_C are the inductive and capacitive "**reactance**", respectively

In a general ac circuit, the v and i amplitudes are related by "**impedance**"

and the **phase angle** ϕ is seen from the phasor diagram to be given by:

Impedance is frequency dependent, making high-pass, low-pass circuits

The average power delivered to an ac circuit depends on the amplitudes of the v and i and on the phase angle ϕ (like a dot product of **phasors**)

In the RLC circuit, the i is maximum (Z minimum) at "**resonance**"

At the resonant frequency, i and v are "in phase", total reactance = 0 and:

A **transformer** transforms the voltage and current levels in an ac circuit.

The ratio of V_{in} (V_1) to V_{out} (V_2) is = to the turns-ratio (ideal transformer)

The current ratio is opposite, so that [power in] = [power out]

Maxwell's equations predict the existence of **electromagnetic waves** that

propagate in vacuum at the **speed of light** c . That's what **light is**.

E and B are uniform over a plane perpendicular to propagation (plane wave)

Electromagnetic waves are **transverse** w/ "in phase" sinusoidal field oscillations. E , B are \perp to each other and the propagation direction.

" k " is the **wave number** of the propagating electromagnetic wave

There are two possible **polarizations** of light for x-propagation (E in y or E in z)

For an electromagnetic wave traveling in a dielectric (eg. glass) $v < c$

The period T , wavelength λ , and frequency f are related to wave speed v :

The **energy density** of a traveling electromagnetic wave is $\frac{1}{2}$ in E , $\frac{1}{2}$ in B

Poynting vector S is energy flow rate (power per unit area) for EM wave

The magnitude of the time-averaged value of S is called **intensity** I of wave

Electromagnetic waves also carry momentum, exerting **radiation pressure**

The radiation pressure p_{rad} of full intensity sunlight is small but measurable

The **flow rate of electromagnetic momentum** (p) is related to S and c

If a perfectly reflecting surface is placed at $x=0$, the incident and reflected

waves add up to form a "**standing wave**" with **nodal planes** of E & B

Standing E-M waves have stationary sinusoidal oscillations

There is an E-node at the mirror: There can be no tangential E on a conducting surface

The E & B variations for a standing E-M wave have E & B "out of phase"

Because the E and B are "out of phase", there is no net flow of energy

If there is **another** mirror parallel to the first one, there **must** be an E-node

there too. This **optical cavity** is the basis of the **laser**, and can only support the **special** wavelengths of light that have nodes at both ends.

The different **colors** of light correspond to different wavelengths λ

Visible light is but a small part of the **spectrum** of electromagnetic waves

$$I_{rms} = I_{max} / \sqrt{2}$$

$$V_{rms} = V_{max} / \sqrt{2}$$

$$i = I \cos(\omega_{applied} t)$$

$$v = V \cos(\omega_{applied} t + \phi)$$

$$V_R = I R$$

$$V_L = I X_L$$

$$V_C = I X_C$$

$$X_L = \omega L ; X_C = 1 / \omega C$$

$$V = I Z \quad Z = \sqrt{R^2 + [X_L - X_C]^2}$$

$$\tan(\phi) = (\omega L - 1 / (\omega C)) / R$$

(Z and ϕ above for *series* circuit)

$$P_{ave} = \frac{1}{2} V I \cos(\phi)$$

$$\text{or } P_{ave} = V_{rms} I_{rms} \cos(\phi)$$

$$\omega_0 = \sqrt{1/(LC)}$$

$$Z = R \quad (\text{at resonance})$$

$$V_2 / V_1 = N_2 / N_1$$

$$V_1 I_1 = V_2 I_2$$

$$c = \sqrt{1/(\epsilon_0 \mu_0)} = 2.998 \times 10^8 \text{ m/s}$$

$$E = c B$$

$$E(x, t) = E_{max} \cos(kx - \omega t)$$

$$B(x, t) = B_{max} \cos(kx - \omega t)$$

$$k = 2\pi/\lambda \quad E_{max} = c B_{max}$$

$$v^2 = 1/(\epsilon \mu) = c^2 / K K_m$$

$$f = 1/T \quad v = \lambda/T = f\lambda$$

$$u_{tot} = u_E + u_B = 2 u_E = \epsilon_0 E^2$$

$$S = E \times B / \mu_0$$

$$I = S_{av} = E_{max} B_{max} / (2\mu_0) = E_{max}^2 / (2\mu_0 c)$$

$$p_{rad} = I / c \quad (\perp \text{ absorbed})$$

$$p_{rad} = 2 I / c \quad (\perp \text{ reflected})$$

$$\frac{1}{A} dp/dt = S / c = EB / (\mu_0 c)$$

$$E\text{-nodes at } kx = n \pi$$

$$B\text{-nodes at } kx = (n + \frac{1}{2}) \pi$$

$$E_y(x, t) = -2E_{max} \sin(kx) \sin(\omega t)$$

$$B_z(x, t) = -2B_{max} \cos(kx) \cos(\omega t)$$

$$I = S_{av} = 0 \quad (\text{standing wave})$$

$$\lambda = c / f = 2 \pi c / \omega$$

$$\lambda_\gamma < \lambda_{xray} < \lambda_{uv} < \lambda_{vis} < \lambda_{ir} < \lambda_{\mu wav} < \lambda_{tv/radio}$$