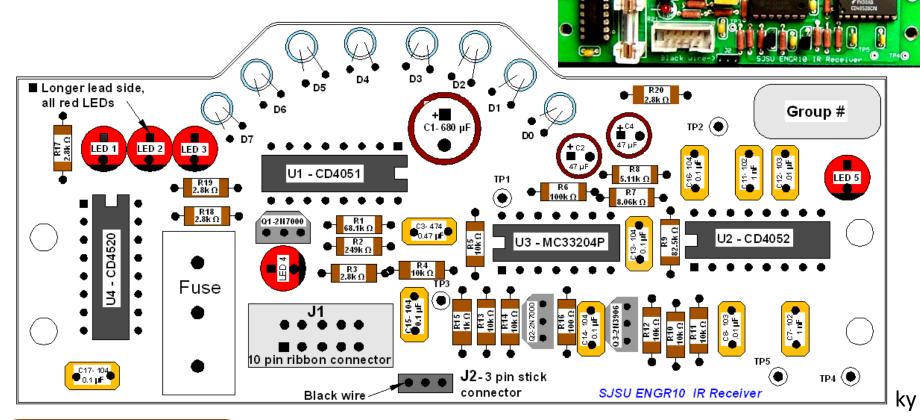
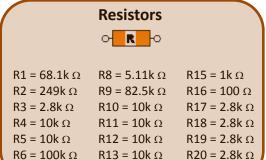
## Robot Project - The IR board





 $R14 = 10k \Omega$ 

 $R7 = 8.06k \Omega$ 

## **Capacitors**

Polarized (+,-)



Non-Polarized

 $C12 = 103, .01 \mu F$  $C1 = 10v 680 \mu F$  $C2 = 10v 47 \mu F$  $C13 = 104, .1 \mu F$  $C3 = 474, .47 \mu F$ 

 $C4 = 10v 47 \mu F$ 

C11 = 102, 1 nF

C7 = 102, 1 nF $C8 = 103, .01 \mu F$ 

C14 = 104,  $.1 \mu F$  $C15 = 104, .1 \mu F$ 

 $C16 = 104, .1 \mu F$ C17 = 104,  $.1 \mu F$  **Transistors** 



Q1 = 2N7000

Q2 = 2N7000Q3 = 2N3906

## **Infrared Detectors**

DO00000



8 - white color

## **LEDs**



5 – red color



U1 = CD4051, 16-pin U2 = CD4052, 16-pin

U3 = MC33204P, 14-pin

U4 = CD4520, 16-pin