## Thick Lenses and the

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## Class Outline

- Properties of Thick Lenses
- Paraxial Ray Matrices
- General Imaging Systems


## Thick Lenses

When the thickness of a lens is not negligible compared to the object and image distances we cannot make the approximations that led to the "thin lens formula", and requires a few additional parameters to describe it

- Front and Back focal lengths
- Primary and secondary Principle planes



## Terms used with Thick Lenses

Focal lengths are measured from the vertex of the lens (not the center) and are labeled as the front focal length and the back focal length. An effective focal length is also often used...

Principle Planes are the plane approximations to the locust of points where parallel incident rays would intersect converging exiting rays. There is a primary (on the front side) and a secondary (on the back side) principle plane. These are located a distance $h_{1}$ and $h_{2}$ from the vertices. These distances are positive when the plane is to the right of the vertex.


## Imaging with a thick lens

The same derivation used for the thin lens equation can be used to show that for a thick lens

$$
\frac{1}{s_{i}}+\frac{1}{s_{o}}=\frac{1}{f}
$$

provide the effective focal length given by

$$
\frac{1}{f}=\left(n_{l}-n_{m}\right)\left[\frac{1}{R_{1}}-\frac{1}{R_{2}}+\frac{\left(n_{l}-n_{m}\right) d_{l}}{n_{l} R_{1} R_{2}}\right]
$$

is used, and the distances $s_{0}$ and $s_{i}$ are measured from the principle points located at

$$
\begin{aligned}
& h_{1}=-\frac{f\left(n_{l}-n_{m}\right) d_{l}}{R_{2} n_{l}} \\
& h_{2}=-\frac{f\left(n_{l}-n_{m}\right) d_{l}}{R_{1} n_{l}}
\end{aligned}
$$



## Thick Lens Parameters



$$
\begin{aligned}
\frac{1}{f} & =\left(n_{l}-n_{m}\right)\left[\frac{1}{R_{1}}-\frac{1}{R_{2}}+\frac{\left(n_{l}-n_{m}\right) d_{l}}{n_{l} R_{1} R_{2}}\right] \\
h_{1} & =-\frac{f\left(n_{l}-n_{m}\right) d_{l}}{R_{2} n_{l}} \quad h_{2}=-\frac{f\left(n_{l}-n_{m}\right) d_{l}}{R_{2} n_{l}}
\end{aligned}
$$

note $h_{1}$ and $h_{2}$ are positive when the principal point is to the right of the vertex

## Example

- For the lens shown, find the effective focal length and the principle points (points where the principle planes intersect the optical axis) if it is made of glass of index 1.5 and is in air 3 mm


Note: Radius of curvature is considered positive if the vertex of the lens surface is to the left of its center of curvature

## Example

- For the lens shown, find the effective focal length and the principle points (points where the principle planes intersect the optical axis) if it is made of glass of index 1.5 and is in air 3 mm

$$
\begin{aligned}
& \frac{1}{f}=(1.5-1)\left[\frac{1}{10 \mathrm{~mm}}-\frac{1}{12 \mathrm{~mm}}+\frac{(1.5-1) 3 \mathrm{~mm}}{1.5(10 \mathrm{~mm})(12 \mathrm{~mm})}\right] \\
& \mathrm{f}=80 \mathrm{~mm}
\end{aligned}
$$

$$
h_{1}=-\frac{80 \mathrm{~mm}(1.5-1) 3 \mathrm{~mm}}{12 \mathrm{~mm}(1.5)}=-6.7 \mathrm{~mm}
$$

$$
h_{2}=-\frac{80 \mathrm{~mm}(1.5-1) 3 \mathrm{~mm}}{10 \mathrm{~mm}(1.5)}=-8 \mathrm{~mm}
$$

## Example

- Find the focal length and locations of the principle points for a thin lens system with two thin lenses of focal lengths 200 mm and -200 mm separated by 100 mm



## Example

- Find the focal length and locations of the principle points for a thin lens system with two thin lenses of focal lengths 200 mm and -200 mm separated by 100 mm

b.f.l $=200 \mathrm{~mm}$ $h_{2}=-200 \mathrm{~mm}$
$\mathrm{f}_{\text {eff }}=400 \mathrm{~mm}$


## Example

- Find the focal length and locations of the principle points for a thin lens system with two thin lenses of focal lengths 200 mm and
-200mm separated by 100 mm

f.f. $=600 \mathrm{~mm}$
$h_{1}=-200 \mathrm{~mm}$
$f_{\text {eff }}=400 \mathrm{~mm}$


## Break



## Compound Optical Systems

- Compound optical systems can be analyzed using ray tracing and the thin and thick lens equations
- A compound optical system can be described in terms of the parameters of a thick lens
- Is there an easier way?

Yes using paraxial ray matrices

## $A B C D$ matrices

- Consider the input and output rays of an optical system. They are lines and so they can be described by two quantities

- Position (r)
- Angle ( $r^{\prime}$ )
- Any optical element must

$$
M=\left[\begin{array}{cc}
A & B \\
C & D
\end{array}\right]
$$ $\begin{aligned} & \text { transform an input ray to an } \\ & \text { output ray, and therefor be }\end{aligned}\left[\begin{array}{l}r_{o u t}^{\prime} \\ r_{o u t}\end{array}\right]=\left[\begin{array}{cc}A & B \\ C & D\end{array}\right]\left[\begin{array}{l}r_{i n}^{\prime} \\ r_{i n}\end{array}\right]$ describable as a $2 \times 2$ matrix

## Free Space Matrix

- Consider an optical system composed of only a length $L$. What is the $A B C D$ matrix



## Refraction Matrix

- Consider an optical system composed of only an interface from a material of index $n_{1}$ to one of index $n_{2}$ What is the ABCD matrix


$$
M=\left[\begin{array}{cc}
n_{1} / n_{2} & 0 \\
0 & 1
\end{array}\right]
$$

## Slab matrix

- What is the $A B C D$ matrix for propagation through a slab of index $n$ and thickness $L$ ?



## Curved surface

- Consider a ray displaced from the optical axis by an amount $r$. The normal to the surface at that point is at an angle $r / R$. The ray's angle with respect to the optical axis if $r^{\prime}$, so its angle with respect to the normal of the surface is $\theta=r^{\prime}+r / R$



## Thick Lens

- A thick lens is two spherical surfaces separated by a slab of thickness d


$$
M=\left[\begin{array}{cc}
n_{2} / n_{1} & \left(n_{2} / n_{1}-1\right) / R_{2} \\
0 & 1
\end{array}\right]\left[\begin{array}{ll}
1 & 0 \\
L & 1
\end{array}\right]\left[\begin{array}{cc}
n_{1} / n_{2} & \left(n_{1} / n_{2}-1\right) / R_{1} \\
0 & 1
\end{array}\right]
$$

## Thin Lens

- For a thin lens we can use the matrix for a thick lens and set $d \rightarrow 0$
- Alternatively we can make geometrical arguments

$$
\begin{array}{r}
r^{\prime}{ }_{\text {in }}=r / s_{0} \quad \stackrel{\downarrow}{\uparrow} \underset{\substack{\text { in }}}{r_{\text {out }}=r_{\text {in }}}{ }^{\prime}{ }^{\prime}{ }_{\text {out }}=-r / s_{\text {i }}=-r\left(1 / f-1 / s_{0}\right)=r_{\text {in }}^{\prime}-r / f \\
M=\left[\begin{array}{cc}
1 & -1 / f \\
0 & 1
\end{array}\right]
\end{array}
$$

## Curved Mirrors

- For a thin lens we can use the matrix for a thin lens and set $f \rightarrow-R / 2$
- Alternatively we can make geometrical arguments


$$
\begin{gathered}
\theta_{\text {in }}=r^{\prime}{ }_{i n}+r / R \\
\theta_{\text {out }}=r^{\prime} \text { out }+r / R=-\theta_{\text {in }}
\end{gathered}
$$

When you reflect off a mirror, the direction

$$
M=\left[\begin{array}{cc}
1 & 2 / R \\
0 & 1
\end{array}\right]
$$

from which you measure $r^{\prime}$ gets flipped.
Also note in this example $R<0$

## Curved Mirror Correction

- For rays emanating from a point off the optical axis the curvature of the mirror that is seen by the rays is distorted
- For tangential rays $R \rightarrow R \cos \theta$
- For sagittal rays $R \rightarrow R / \cos \theta$


$$
\begin{array}{r}
12=\left[\begin{array}{cc}
1 & 2 / R \\
0 & 1
\end{array}\right] \\
\\
\end{array}
$$

## Example

- Find the back focal length of the following compound system



## Example

Step 1, find the ABCD matrix for the system

$$
\begin{gathered}
M=\left[\begin{array}{cc}
1 & -1 / f \\
0 & 1
\end{array}\right]\left[\begin{array}{ll}
1 & 0 \\
d & 1
\end{array}\right]\left[\begin{array}{cc}
1 & -1 / f \\
0 & 1
\end{array}\right] \\
M=\left[\begin{array}{cc}
1 & -1 / f \\
0 & 1
\end{array}\right]\left[\begin{array}{cc}
1 & -1 / f \\
d & 1-d / f
\end{array}\right] \\
M=\left[\begin{array}{cc}
1-d / f & -2 / f+d / f^{2} \\
d & 1-d / f
\end{array}\right] \\
{\left[\begin{array}{c}
-2 r / f+d r / f^{2} \\
r-r d / f
\end{array}\right]=\left[\begin{array}{cc}
1-d / f & -2 / f+d / f^{2} \\
d & 1-d / f
\end{array}\right]\left[\begin{array}{l}
0 \\
r
\end{array}\right]_{12.24}}
\end{gathered}
$$

## Example

Step 2. Require input rays parallel to the optical axis pass through the optical axis after the lens system and an additional path length equal to the back focal length

$$
\left[\begin{array}{c}
r_{\text {out }}^{\prime} \\
0
\end{array}\right]=\left[\begin{array}{cc}
1 & 0 \\
b . f . l . & 1
\end{array}\right]\left[\begin{array}{cc}
1-d / f & -2 / f+d / f^{2} \\
d & 1-d / f
\end{array}\right]\left[\begin{array}{c}
0 \\
r_{\text {in }}
\end{array}\right]
$$

Step 3. solve for b.f.l.

$$
\begin{gathered}
0=\left(b . f . l .\left(-2 / f+d / f^{2}\right)+1-d / f\right) r_{i n} \\
\text { b.f.l. }=\frac{1-d / f}{-2 / f+d / f^{2}}=\frac{f^{2}-d f}{d-2 f}
\end{gathered}
$$

## Example

After how many round trips will the beam be re-imaged onto itself? (this is called a "stable resonator")


## Example

Step 1. Find the $A B C D$ matrix for 1 round trip

$$
\begin{gathered}
M_{r t}=\left(\left[\begin{array}{cc}
1 & -2 / R \\
0 & 1
\end{array}\right]\left[\begin{array}{ll}
1 & 0 \\
d & 1
\end{array}\right]\right)^{2} \\
M_{r t}=\left[\begin{array}{cc}
1-2 d / R & -2 / R \\
d & 1
\end{array}\right]^{2}
\end{gathered}
$$



Step 2. Require that after $N$ round trips the ray returns to its original state

$$
M_{r t}^{N}=1
$$

## Example


so

$$
\lambda_{o w}^{2 N}=\lambda_{r t}^{N}=\lambda_{N}=1 \quad \text { from } \quad M_{r t}^{N}=1
$$

thus

$$
\begin{gathered}
\lambda_{o w}=e^{ \pm i \theta} \\
\text { where }
\end{gathered} 2 N \theta=2 \pi m \text { } \begin{array}{cc} 
\\
M_{o w}-I \lambda_{o w}=\left[\begin{array}{cc}
1-2 d / R-\lambda_{o w} & -2 / R \\
d & 1-\lambda_{o w}
\end{array}\right]=0
\end{array}
$$

## Example

Explicitly computing $\lambda_{\text {ow }}$ gives


$$
\begin{gathered}
\operatorname{det}\left(M_{o w}-I \lambda_{o w}\right)=\left|\begin{array}{cc}
1-2 d / R-\lambda_{o w} & -2 / R \\
d & 1-\lambda_{o w}
\end{array}\right|=0 \\
\left(1-2 d / R-\lambda_{o w}\right)\left(1-\lambda_{o w}\right)-2 d / R=0 \\
\lambda_{o w}=1-\frac{d}{R} \pm \sqrt{\left(1-\frac{d}{R}\right)-1}=1-\frac{d}{R} \pm i \sqrt{1-\left(1-\frac{d}{R}\right)^{2}} \\
\lambda_{o w}=e^{ \pm i \theta} \quad \text { with } \quad \cos \theta=1-\frac{d}{R}
\end{gathered}
$$

## Example

Relating the expressions for $\lambda_{\text {ow }}$
$2 N \theta=2 \pi m \quad$ and $\quad \cos \theta=1-\frac{d}{R}$


$$
N=\frac{\pi m}{\cos ^{-1}\left(1-\frac{d}{R}\right)}
$$

The so-called "g-factor" for a resonator is $g=\cos \theta=1-d / R$. Note the beam can only be re-imaged onto itself if $d<2 R$. Another way of saying that is $0 \leq g^{2} \leq 1$ the "stability criterion" for a resonator.

## Summary

- Thick lenses require more parameters to describe than thin lenses
- If the parameters of a thick lens are properly described, its imaging behavior can be determined using the thin lens equation
- ABCD matrices are convenient ways to deal with the propagation of rays through an arbitrary optical system

